

# 取扱いおよび設置説明書

## 電子式セーフティセンサー RSS 36-I2-D

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## 1 About this document

### 1.1 Function

This document provides all the information you need for the mounting, set-up and commissioning to ensure the safe operation and disassembly of the switchgear. The operating instructions enclosed with the device must always be kept in a legible condition and accessible.

### 1.2 Target group of the operating instructions: authorised qualified personnel

All operations described in the operating instructions manual must be carried out by trained specialist personnel, authorised by the plant operator only.

Please make sure that you have read and understood these operating instructions and that you know all applicable legislations regarding occupational safety and accident prevention prior to installation and putting the component into operation.

The machine builder must carefully select the harmonised standards to be complied with as well as other technical specifications for the selection, mounting and integration of the components.

The information contained in this operating instructions manual is provided without liability and is subject to technical modifications.

### 1.3 Explanation of the symbols used



Information, hint, note: This symbol is used for identifying useful additional information.



Caution: Failure to comply with this warning notice could lead to failures or malfunctions.  
Warning: Failure to comply with this warning notice could lead to physical injury and/or damage to the machine.

### 1.4 Appropriate use

The Schmersal range of products is not intended for private consumers.

The products described in these operating instructions are developed to execute safety-related functions as part of an entire plant or machine. It is the responsibility of the manufacturer of a machine or plant to ensure the correct functionality of the entire machine or plant.

The safety switchgear must be exclusively used in accordance with the versions listed below or for the applications authorised by the manufacturer. Detailed information regarding the range of applications can be found in the chapter “Product description”.

### 1.5 General safety instructions

The user must observe the safety instructions in this operating instructions manual, the country specific installation standards as well as all prevailing safety regulations and accident prevention rules.



Further technical information can be found in the Schmersal catalogues or in the online catalogue on the Internet: [products.schmersal.com](http://products.schmersal.com).

## 2 Product description

### 2.1 Ordering code

Product type description:  
RSS 36 (1)–(2)–(3)–(4)–(5)–(6)

(1)	
without	Standard coding
I1	Individual coding
I2	Individual coding, multiple teaching

(2)	
<b>without</b>	Without diagnostic function (only on request <sup>1)</sup> )
<b>D</b>	With diagnostic output
<b>SD</b>	With serial diagnostic function <sup>2)</sup>

(3)	
<b>without</b>	Standard version without feedback circuit monitoring EDM (External Device Monitoring)
<b>F0</b>	EDM with automatic reset <sup>2)</sup>
<b>F1</b>	EDM with manual reset <sup>2)</sup>

(4)	
<b>without</b>	Without EMERGENCY STOP
<b>Q</b>	Acknowledge input error with EMERGENCY STOP <sup>2)</sup>

(5)	
<b>without</b>	Without latching
<b>R</b>	With latching, latching force approx. 18 N

(6)	
<b>ST</b>	Connector plug M12, 8-pole
<b>ST5</b>	Connector plug M12, 5-pole

(*)	
<sup>1)</sup>	only for version –ST5
<sup>2)</sup>	only for version –ST

## 2.2 Special versions

For special versions, which are not listed in the ordering code, these specifications apply accordingly, provided that they correspond to the standard version.

## 2.3 Purpose

This non-contact, electronic safety sensor is designed for application in safety circuits and is used for monitoring the position of movable safety guards. In this application, the safety sensor monitors the position of hinged, sliding or removable safety guards by means of the coded electronic actuator.

The safety function consists of safely switching off the safety outputs when the safety guard is opened and maintaining the safe switched off condition of the safety outputs for as long as the safety guard is open.



The safety switchgears are classified according to ISO 14119 as type 4 interlocking devices. Designs with individual coding are classified as highly coded.

Safety sensors and actuators with latching (ordering suffix 'R') always must be used in pairs. The latching force (approx. 18 N) exercised by the permanent magnet keeps hatches and small guards closed, also in a de-energised condition.

The system can be used as a door end stop up to 5 kg at 0.25 m/s.

With the F0/F1 option, the sensor performs the tasks of a safety-monitoring module. At both safety outputs, two auxiliary contactors<sup>1)</sup> or Relays<sup>1)</sup> (1) each with positive-action contacts in accordance with EN 60947-5-1 or EN 50205) can be connected, whose safety-related function is checked by the sensor by means of a feedback circuit (External Device Monitoring). The feedback circuit includes the series-wiring of the NC contacts of the auxiliary contactors or relays. For the F0 version, an “enabling switch” (without safety function) can be integrated into the feedback circuit. For the F1 version, a so-called “reset button” is required, which is monitored for a trailing edge. This function corresponds to the “manual reset function” to EN ISO 13849-1.

The Q option monitors simultaneous shutdown of the sensor inputs. Series-wired sensors enable integration of EMERGENCY STOP switching elements for applications to PL<sub>e</sub>. The EMERGENCY STOP contacts are supplied by the cross-circuit monitored output signals of an upstream electronic safety switchgear device. At the end of the chain, a sensor with Q option for connecting an acknowledgement function monitors the chain for synchronous shutdown of both channels. In the event of erroneous shutdown, the error must be rectified. The safety outputs can be reactivated only once the error has been acknowledged.

The diagnostic output of the safety sensor alternatively can be used as a conventional output or as a “serial output “ with input and output channel.

**Series-wiring**

Series-wiring can be set up. In the case of a series connection, the risk time remains unchanged and the reaction time increases by the sum of the reaction time of the inputs per additional unit specified in the technical data. The quantity of devices is only limited by the cable drops and the external cable fuse protection, according to the technical data. Up to 31 device variants with serial diagnostics can be wired in series.



The user must evaluate and design the safety chain in accordance with the relevant standards and the required safety level. If multiple safety sensors are involved in the same safety function, the PFH values of the individual components must be added.



The entire concept of the control system, in which the safety component is integrated, must be validated to the relevant standards.

**2.4 Warning about misuse**



In case of improper use or manipulation of the safety switchgear, personal hazards or damages to machinery or plant components cannot be excluded. There are no residual risks, provided that the safety instructions as well as the instructions regarding mounting, commissioning, operation and maintenance are observed.

**2.5 Exclusion of liability**

We shall accept no liability for damages and malfunctions resulting from defective mounting or failure to comply with the operating instructions manual. The manufacturer shall accept no liability for damages resulting from the use of unauthorised spare parts or accessories.

For safety reasons, invasive work on the device as well as arbitrary repairs, conversions and modifications to the device are strictly forbidden, the manufacturer shall accept no liability for damages resulting from such invasive work, arbitrary repairs, conversions and/or modifications to the device.

**3 Technical data**

**認証**

証明書	TÜV cULus ECOLAB FCC IC ANATEL
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一般データ

規格	EN ISO 13849-1 EN IEC 60947-5-3 EN IEC 61508
一般情報	個別コード化 複数のティーチング
Coding level according to EN ISO 14119	High
アクティブ原理	RFID
周波数帯、RFID	125 kHz
送信機出力 RFID、最大	-6 dB/m
ハウジング形状	ブロック型
取り付け条件（機械式）	不適切な
センサートポロジー	直列配線用センサー
ハウジング 材質	グラスファイバー強化熱可塑性樹脂
応答時間、最大	100 ms
リスク持続時間、最大	200 ms
アクチュエーターの応答時間、最大	100 ms
入力の応答時間、最大	0.5 ms
総重量	80 g

一般データ - 仕様

診断出力	Yes
短絡検出	Yes
短絡監視	Yes
直列接続	Yes
安全機能	Yes
カスケード可能	Yes
一体型システム診断、状態	Yes
LEDの数	3
信号機能付き半導体出力の数	1
フェイルセーフデジタル出力の数	2

安全性評価

規格	EN ISO 13849-1 EN IEC 61508
Performance Level, up to	e
カテゴリ	4
PFH値	$2.70 \times 10^{-10}$ /h
PFD値	$2.10 \times 10^{-5}$
安全性整合性レベル（SIL）	3
Mission time	20 年

機械的データ

作動パネル	側面
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作動範囲	側面
機械的寿命、最小	1,000,000 操作
Note (Mechanical life)	Actuating speed 0.25 m/s Operations for door weights ≤ 5 kg
取り付け	A screw length of 25 mm is sufficient for sensor mounting and for side mounting of the actuators. 30 mm long screws are recommended when the actuator is mounted upright and/or when the sealing discs are used.
Type of the fixing screws	2x4M (DIN 125A/フォームAによるワッシャー付きシリンダーネジ)
取り付けネジの締め付けトルク、最小	2.2 Nm
Tightening torque of the fixing screws, maximum	2.5 Nm

## Mechanical data – Switching distances

切替距離、典型的な	12 mm
確実な切替距離「ON」	10 mm
確実な切替距離「OFF」	16 mm
注記 (動作距離)	All switching distances in accordance EN IEC 60947-5-3
ヒステリシス (切替距離), 最大	2 mm
切換位置再現性 R	0.5 mm
注意 (繰り返し精度R)	Axial offset: The long side allows for a maximum height misalignment (x) of sensor and actuator of 8 mm (e.g. mounting tolerance or due to guard door sagging). The axial misalignment (y) is max. ± 18 mm (see figure: Operating principle). Minimum clearance between two sensor systems 100 mm.

## 機械的データ – 電気機械式

注意 (センサーチェーンの長)	ケーブル長とケーブル径により、出力電流による電圧降下が変化します。
注意 (直列接続)	無制限のデバイス数, 外部ラインヒューズオーバーサージ、シリアル診断SDの場合、最大
ケーブルの長さ	2 m
端子 コネクター	ケーブル (Y-UL 2517), 8芯
ケーブル断面積, 最大	8 x 0.35 mm²
ケーブル径	22 AWG
Cable type	LiYY

## 機械的データ – 寸法

センサー長	22 mm
センサーの幅	106.3 mm
センサーの高さ	25 mm

## 環境条件

保護等級	IP65 IP67 IP69
使用周囲温度	-28 ... +70 ° C
保管および輸送温度	-28 ... +85 ° C
ケーブルの耐熱性材質 (動作時)、最小	-10 ° C
ケーブルの耐熱性材質 (保存時)、最小	-30 ° C

相対湿度, 最大	93 %
Note (Relative humidity)	non-condensing non-icing
耐振動	10 ~ 55 Hz, 振幅 1 mm
耐衝撃	30 g / 11 ms
Protection class	III
Permissible installation altitude above sea level, maximum	2,000 m

## 環境条件 - 絶縁値

定格絶縁電圧	32 VDC
定格インパルス耐電圧	0.8 kV
Overvoltage category	III
汚染度	3

## 電気的データ

動作電圧	24 VDC -15 % / +10 % (PELV電源により安定化)
動作電流、最小	0.5 mA
無負荷供給電流 $I_0$ , 典型的	35 mA
定格動作電圧	24 VDC
動作電流	600 mA
要求定格短絡電流	100 A
準備時間、最大	2,000 ms
開閉頻度、最大	1 Hz
使用カテゴリ DC-12	24 VDC / 0.05 A
電気的ヒューズ定格、最大	2 A

## Electrical data - Safety digital inputs

Designation, Safety inputs	X1 and X2
Current consumption of the safety inputs	5 mA
テストパルス幅、最大	1 ms
テストパルス間隔、最小	100 ms
Classification ZVEI CB24I, Sink	C1
Classification ZVEI CB24I, Source	C1 C2 C3

## Electrical data - Safety digital outputs

Designation, Safety outputs	Y1 and Y2
定格動作電流（安全出力）	250 mA
出力電流、（フェイルセーフ出力）、最大	0.25 A
安全出力	short-circuit proof, p-type
Voltage drop $U_d$ , maximum	1 V
Leakage current $I_r$ , maximum	0.5 mA

Voltage, Utilisation category DC-12	24 VDC
Current, Utilisation category DC-12	0.25 A
Voltage, Utilisation category DC-13	24 VDC
Current, Utilisation category DC-13	0.25 A
テストパルス間隔、標準	1000 ms
テストパルス幅、最大	0.3 ms
Classification ZVEI CB24I, Source	C2
Classification ZVEI CB24I, Sink	C1 C2

## 電氣的データ - 診断出力

Designation, Diagnostic outputs	OUT
Design of control elements	short-circuit proof, p-type
Voltage drop $U_d$ , maximum	2 V
Voltage, Utilisation category DC-12	24 VDC
Current, Utilisation category DC-12	0.05 A
Voltage, Utilisation category DC-13	24 VDC
Current, Utilisation category DC-13	0.05 A

## 電氣的データ - 電磁両立性 (EMC)

Interfering radiation	IEC 61000-6-4
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## 状態表示

Note (LED switching conditions display)	LED yellow: Operating condition LED green: Supply voltage LED red: Fault
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## ピン配列

PIN 1	1A1 Ue: (1)
PIN 2	X1 Safety input 1
PIN 3	A2 GND Blue
PIN 4	Y1 Safety output 1 Black
PIN 5	OUT Diagnostic output OUT Grey
PIN 6	X2 Safety input 2 violet
PIN 7	Y2 Safety output 2 red
PIN 8	IN without function Pink

## FCC/IC - Note

This device complies with Part 15 of the FCC Rules and contains licence-exempt transmitter/receivers that are compliant with ISSED (Innovation, Science and Economic Development) Canada licence-exempt RSS standard(s).

Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference signals, and
- (2) This device must be able to tolerate interference signals. These also include interference signals that could cause the device to function improperly.

This device complies with the nerve stimulation limits (ISED SPR-002) when operated at a minimum distance of 100 mm. Changes or modifications not expressly approved by K.A. Schmersal GmbH & Co. KG could void the user's authority to operate the equipment.



The licence-free transmitter/receiver contained in this device satisfies the requirements of the "Radio Standards Specification" of the Innovation, Science and Economic Development Canada (ISED) authority that apply to licence-free radio equipment. Operation is permissible under the following two conditions:

(1) The device must not create disturbances.

(2) The device must tolerate received radio frequency interference, even if this could impair its functionality.

This device complies with the nerve stimulation limits (ISED CNR-102) when operated at a minimum distance of 100 mm. In the event of changes or modifications that have not been expressly approved by K.A. Schmersal GmbH & Co. KG, the user's authorisation to use the device may become ineffective.



Este equipamento não tem direito à proteção contra interferência prejudicial e não pode causar interferência em sistemas devidamente autorizados.

Para maiores informações consultar: [www.gov.br/anatel](http://www.gov.br/anatel)

## 4 Mounting

### 4.1 General mounting instructions



Please observe the relevant requirements of the standards ISO 12100, ISO 14119 and ISO 14120.

Ensure the safety sensor and actuator is mounted on a flat surface. The component can be mounted in any position. The universal mounting holes provide for a variable mounting by means of M4 screws. Mounting: a screw length of 25 mm is sufficient for sensor mounting and for side mounting of the actuators. 30 mm long screws are recommended when the actuator is mounted upright and/or when the sealing discs are used. (Tightening torque 2,2...2,5 Nm). The labelled surfaces of the safety sensor and the actuator have to be opposite. The safety sensor must only be used within the assured switching distances  $\leq s_{ao}$  and  $\geq s_{ar}$ .



The actuator must be permanently fitted to the safety guards and protected against displacement by suitable measures (tamperproof screws, gluing, drilling of the screw heads).

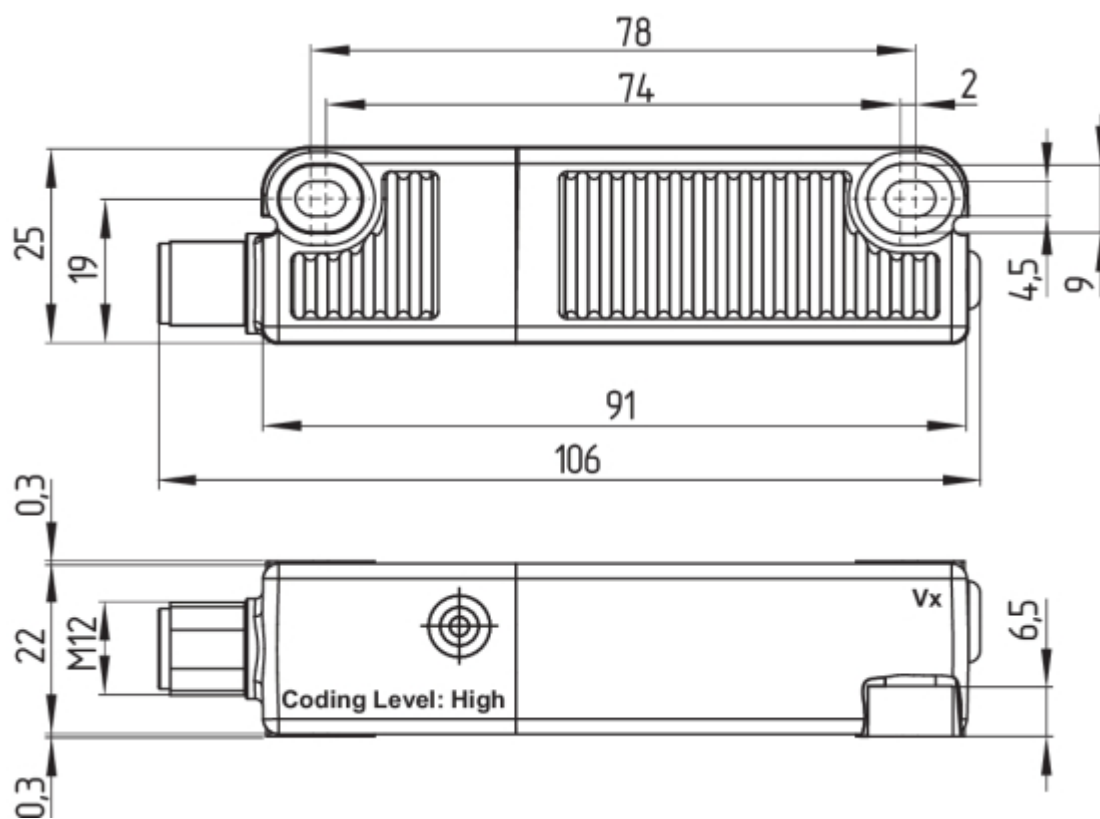
To avoid any interference inherent to this kind of system and any reduction of the switching distances, please observe the following guidelines:

- The presence of metal chips in the vicinity of the sensor is liable to modify the switching distance.
- Keep away from metal chips
- Minimum distance 100 mm between two safety sensors as well as other systems with same frequency (125 kHz)

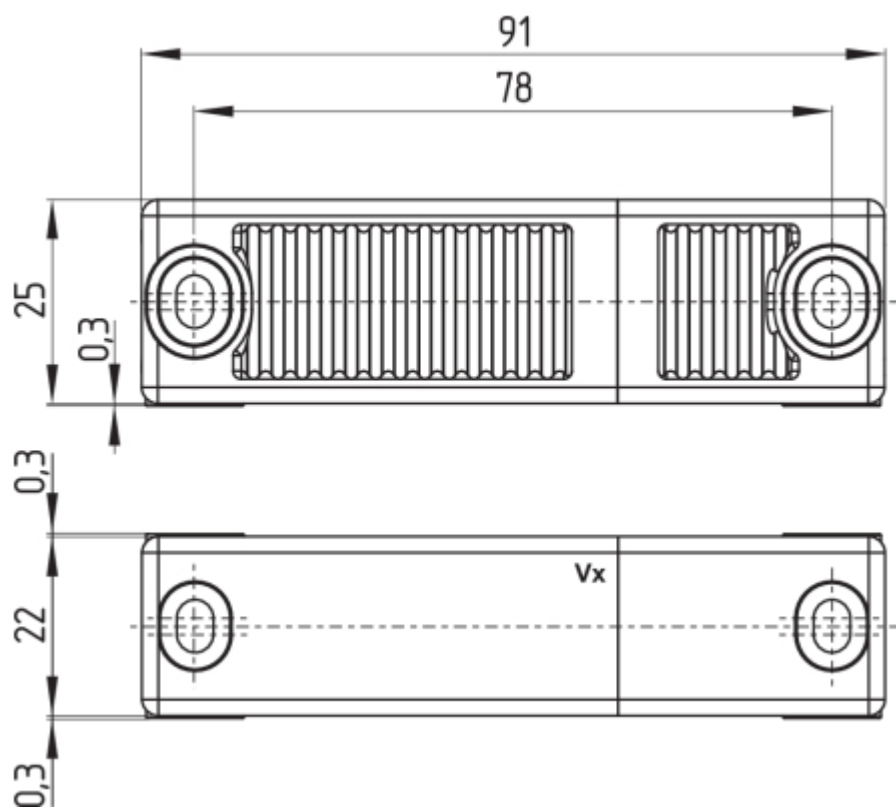
### 4.2 Dimensions

All measurements in mm.

**Safety sensor**



#### Actuator



Alternative suitable actuators with different design: refer to [products.schmersal.com](https://products.schmersal.com).

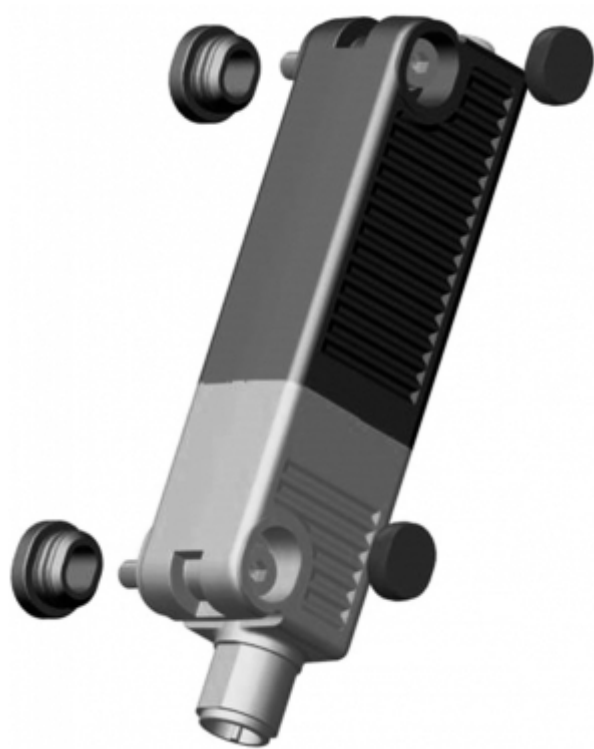
### 4.3 Accessories

**Set of disposable screws (order separately)**

- 4x M4x25 incl. washers, order number 101217746
- 4x M4x30 incl. washers, Bestellnummer 101217747

**Sealing kit (order separately)**

- Order number 101215048
- 8 plugs and 4 under seals
- To seal the mounting holes and as a spacer (approx. 3 mm) to facilitate cleaning below the mounting surface
- Also suitable as tamper protection for the screw attachment



### 4.4 Switch distance

Switching distances in mm to IEC 60947-5-3	
Typical switching distance $s_{typ}$ :	12
Assured switching distance $s_{ao}$ :	10
Assured switch-off distance $s_{ar}$ :	20



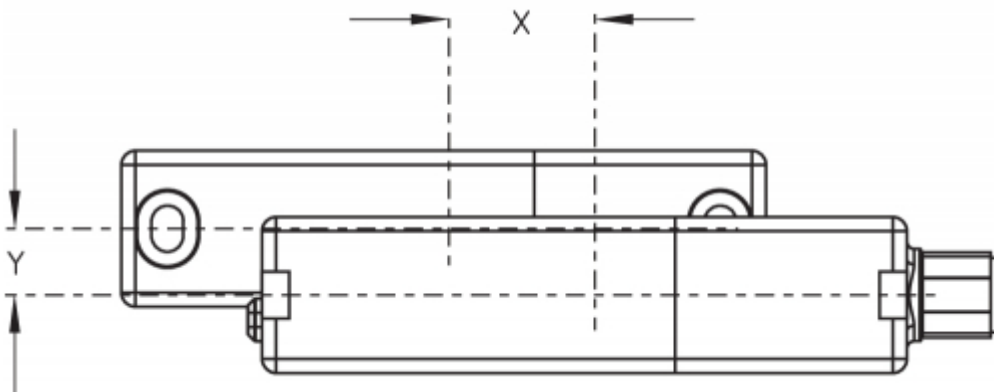
There are new switch distances as per the table below owing to the necessity of technical modifications (as of V2). Please check the design of your guard system following installation to ensure adherence to the secured switch distances ( $\leq s_{ao}$  and  $\geq s_{ar}$ ) in accordance with the specified values and adjust the guard system accordingly. The positions of the designations  $V_x$  should be obtained from the dimensional drawings.

Switching distances in mm to IEC 60947-5-3		Actuator RST	Actuator RST as of V2
Sensor RSS□	$s_{typ}$	12	12
	$s_{ao}$	10	8
	$s_{ar}$	16	16
Sensor RSS as of V2	$s_{typ}$	12	12
	$s_{ao}$	10	10
	$s_{ar}$	20	20



With the combination of "old sensor - new actuator (as of V2)" there may be limitations in availability owing to the reduced  $s_{ao}$  (8 mm). This change has no affect on the performance level.

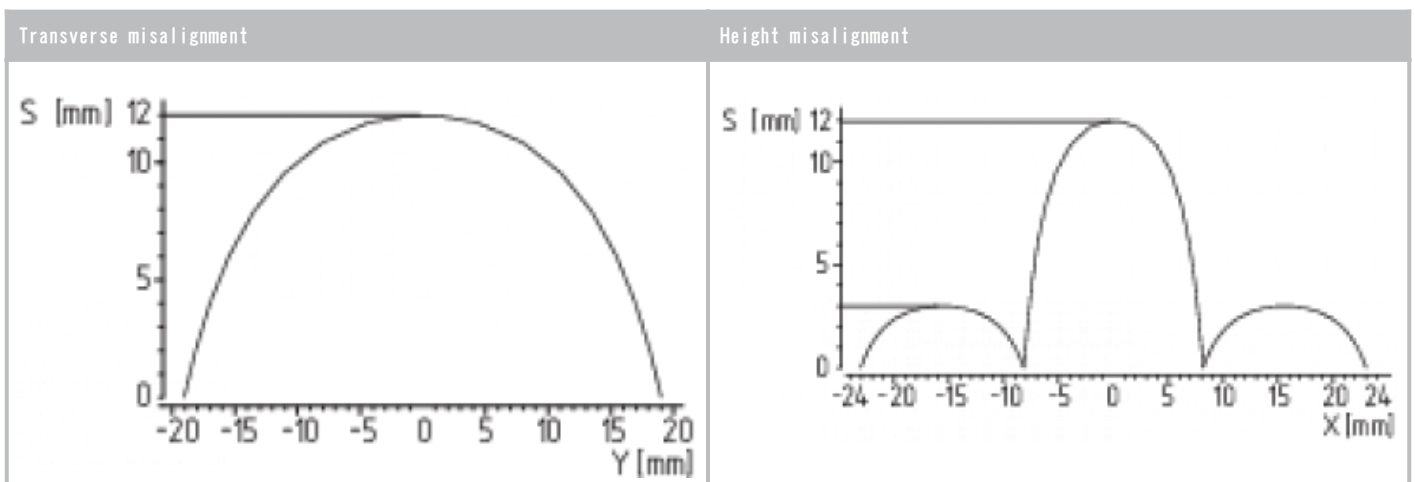
The side allows for a maximum height misalignment (X) of sensor and actuator of  $\pm 8$  mm (e.g. mounting tolerance or due to guard door sagging). The axial misalignment (y) is max.  $\pm 18$  mm.



Latching versions  $X \pm 5$  mm,  $Y \pm 3$  mm.  
The latching force will be reduced by misalignment.

### Actuating curves

The actuating curves represent the typical switching distance of the safety sensor during the approach of the actuator subject to the actuating direction



Preferred actuation directions: from front or from side

## 4.5 Adjustment

The continuous signal of the yellow LED signals the actuator detection; the flashing of the yellow LED signals that the safety sensor is actuated in the hysteresis area.



### Recommended Adjustment

Align the safety sensor and actuator at a distance of  $0.5 \times s_{a0}$ .

The correct functionality of both safety channels must be checked by means of the connected safety-monitoring module.

## 5 Electrical connection

### 5.1 General information for electrical connection



The electrical connection may only be carried out by authorised personnel in a de-energised condition.

The safety outputs can be integrated into the safety circuit of the control system. For applications of PL e / category 4 to EN ISO 13849-1, the safety outputs of the safety sensor or of the sensor chain must be wired to a safety monitoring-module of the same category.

The required electrical cable fuse protection must be integrated in the installation.

Protection is not required when pilot wires are laid. The cables however must be separated from the supply and energy cables. The max. fuse rate for a sensor chain depends on the section of the connecting cable of the sensor.

#### Requirements for the connected safety-monitoring module:

dual-channel safety input, suitable for p-type sensors with NO function



Information for the selection of suitable safety-monitoring modules can be found in the Schmersal catalogues or in the online catalogue on the Internet: [products.schmersal.com](http://products.schmersal.com)

As an alternative to an evaluation unit, the safety sensors of the RSS 36..F0 resp. RSS 36...F1 series can also be used for direct control and monitoring of safety contactors as first sensor of a series-wired chain.

The sensors cyclically switch off the safety output to test them. The safety-monitoring module therefore does not need to be equipped with a cross-wire short detection. The switch-off times must be tolerated by the safety-monitoring module. The switch -off time of the safety sensor is additionally extended depending on the cable length and the capacity of the cable used. Typically, a switch-off time of  $250 \mu s$  is reached with a 30-m connecting cable.



#### Configuration of the safety-monitoring module

If the safety sensor is connected to electronic safety-monitoring modules, we recommend that you set a discrepancy time of min. 100 ms. The safety inputs of the safety-monitoring module must be able blanking a test impulse of approx. 1 ms. The safety-monitoring module does not need to have a cross-wire short monitoring function, if necessary, the cross-wire short monitoring function must be disabled.

### 5.2 Serial diagnostic -SD

#### Cable design

The wiring capacitance of the connecting cable of the safety sensor must not exceed 50 nF.

Depending on the strand structure, normal unshielded 200 m long control cables LIYY 0.25 mm<sup>2</sup> to 1.5 mm<sup>2</sup> have a wiring capacitance of approx. 20 ... 50 nF



On wiring SD devices, please pay attention to the voltage drop on the cables and the current carrying capacity of the individual components.



#### Accessories for the series-wiring

For convenient wiring and series-wiring of SD components, the SD junction boxes PFB-SD-4M12-SD-V2 (variant for the field) and PDM-SD-4CC-SD (variant for control cabinet on carrier rail) are available along with additional comprehensive accessories. Detailed information is available on the Internet, [products.schmersal.com](http://products.schmersal.com).

## 5.3 Wiring examples for series-wiring

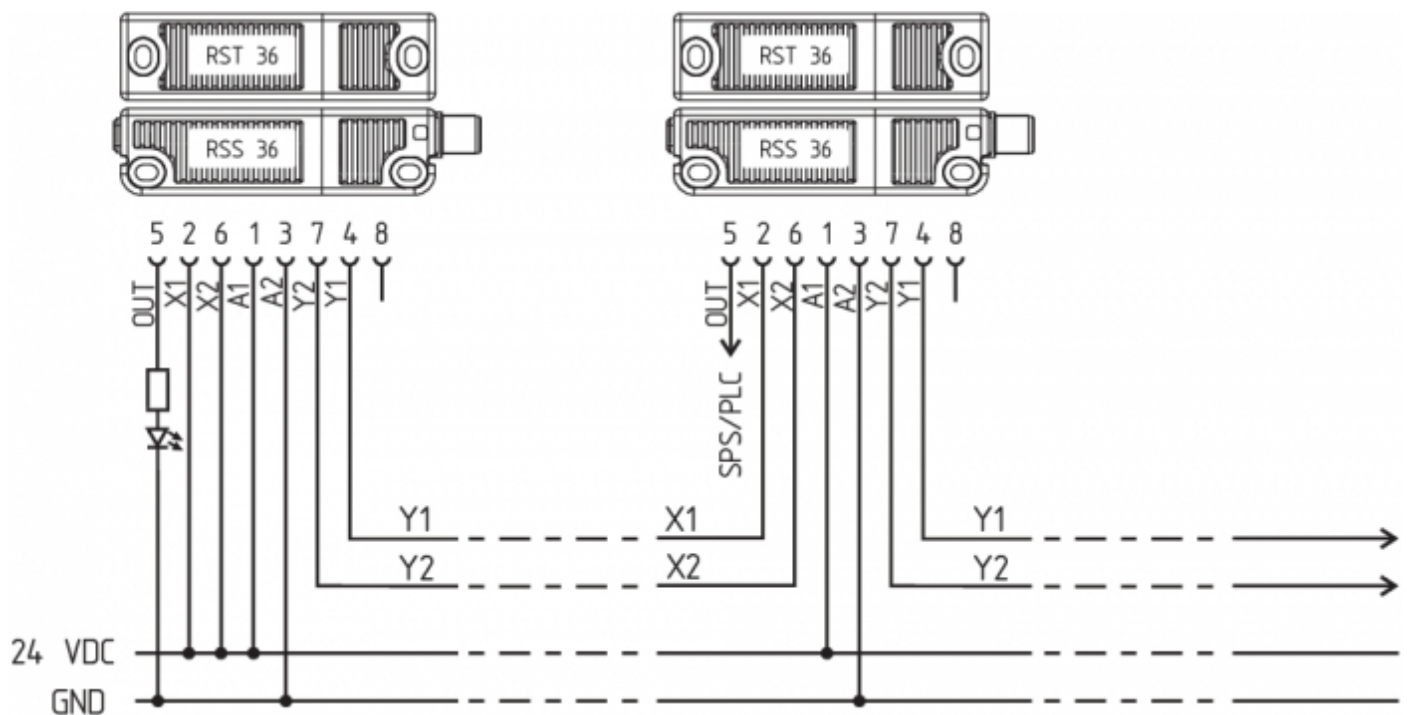
Series-wiring can be set up. In the case of a series connection, the risk time remains unchanged and the reaction time increases by the sum of the reaction time of the inputs per additional unit specified in the technical data. The number of components is only limited by the external cable protection according to the technical data and the line loss. Series-wiring of up to 31 RSS 36 ... SD components with serial diagnostics is possible.

The application examples shown are suggestions. They however do not release the user from carefully checking whether the switchgear and its set-up are suitable for the individual application. The application examples shown are suggestions.

### Wiring example 1: Series-wiring of the RSS 36 with conventional diagnostic output

The voltage is supplied to both safety inputs of the last safety sensor of the chain (considered from the safety-monitoring module).

The safety outputs of the first safety sensor are wired to the safety-monitoring module. The diagnostic output can be connected for instance to a PLC.

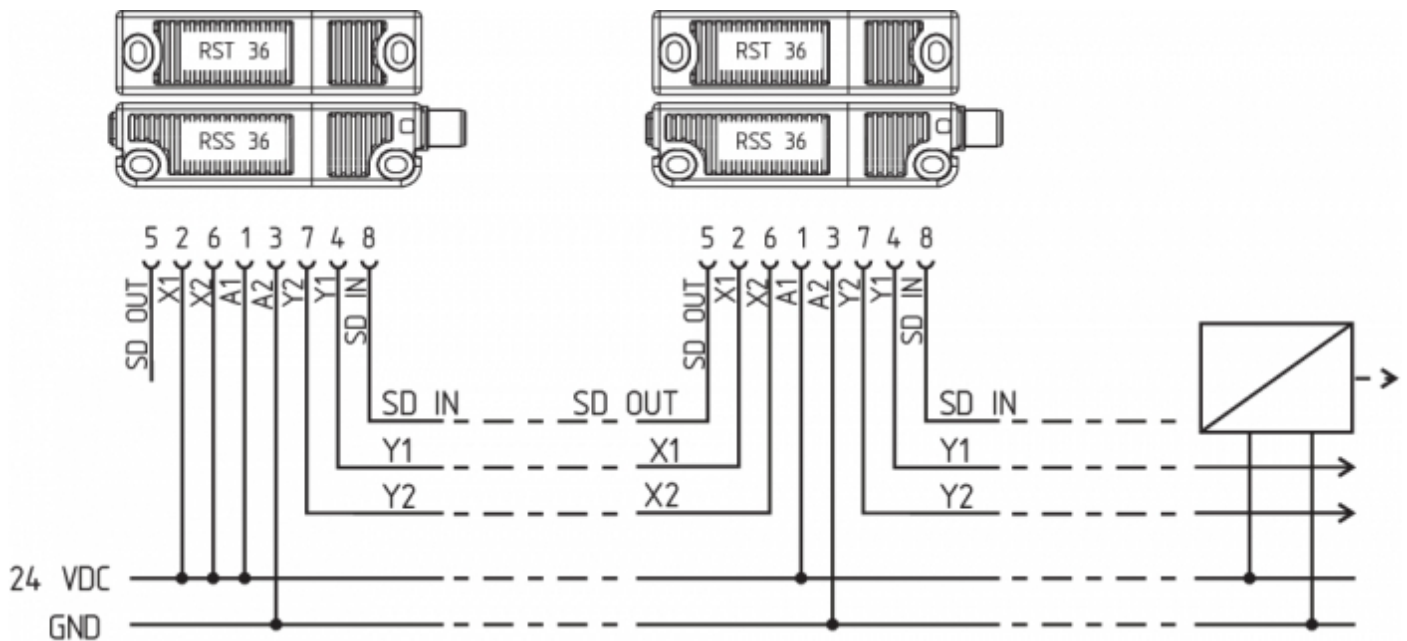


Y1 and Y2 = Safety outputs → Safety monitoring module

### Wiring example 2: series-wiring of the RSS 36 with serial diagnostic function

In devices with the serial diagnostics function (ordering suffix -SD), the serial diagnostics connections are wired in series and connected to a SD-Gateway for evaluation purposes. The voltage is supplied to both safety inputs of the last safety sensor of the chain (considered from the safety-monitoring module).

The safety outputs of the first safety sensor are wired to the safety-monitoring module. The serial Diagnostic Gateway is connected to the serial diagnostic input of the first safety sensor.

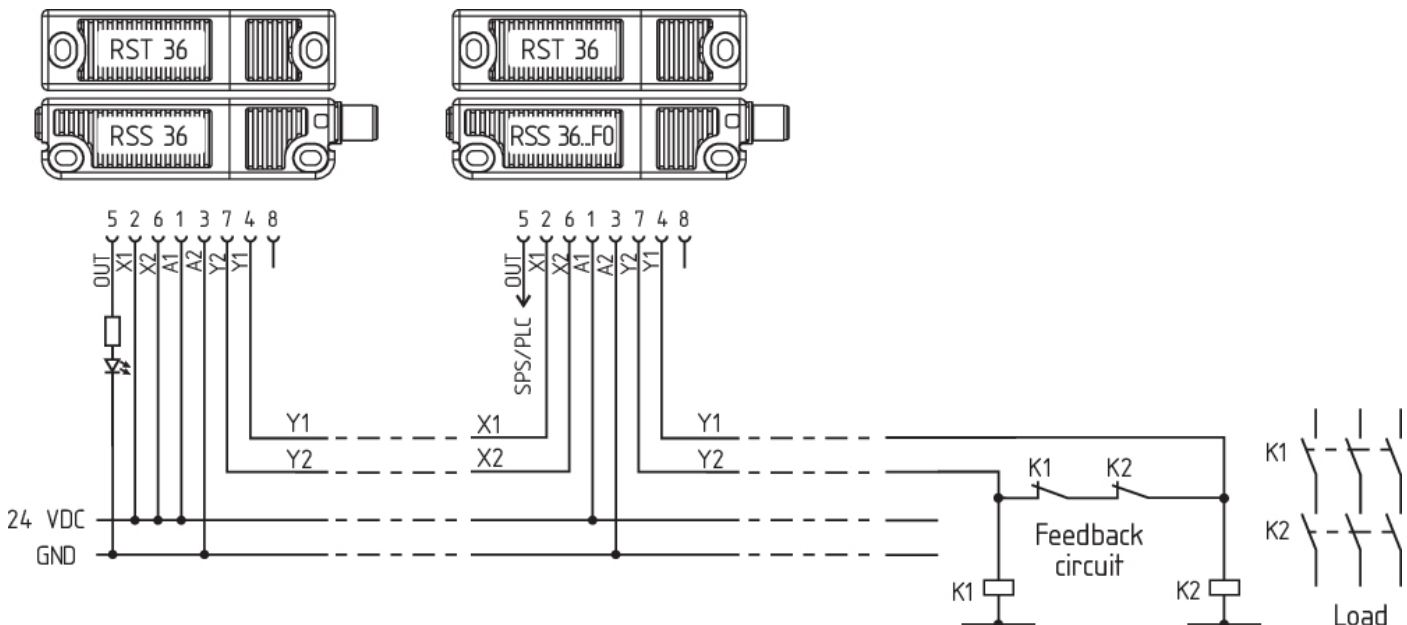


Y1 and Y2 = Safety outputs → Safety monitoring module  
SD-IN → Gateway → Field bus

#### Wiring example 3: Series-wiring with RSS 36...F0

The safety sensor RSS 36 ...F0 directly controls positive-action auxiliary contactors or relays. The monitoring of the external contactors or relays is enabled by the feedback circuit, which is built by the NC contacts of K1, K2. As no further button is used, the auxiliary contactors or relays are immediately enabled when the safety guard is closed. This kind of automatic reset is permissible only if a hazard from the machine starting up can be ruled out.

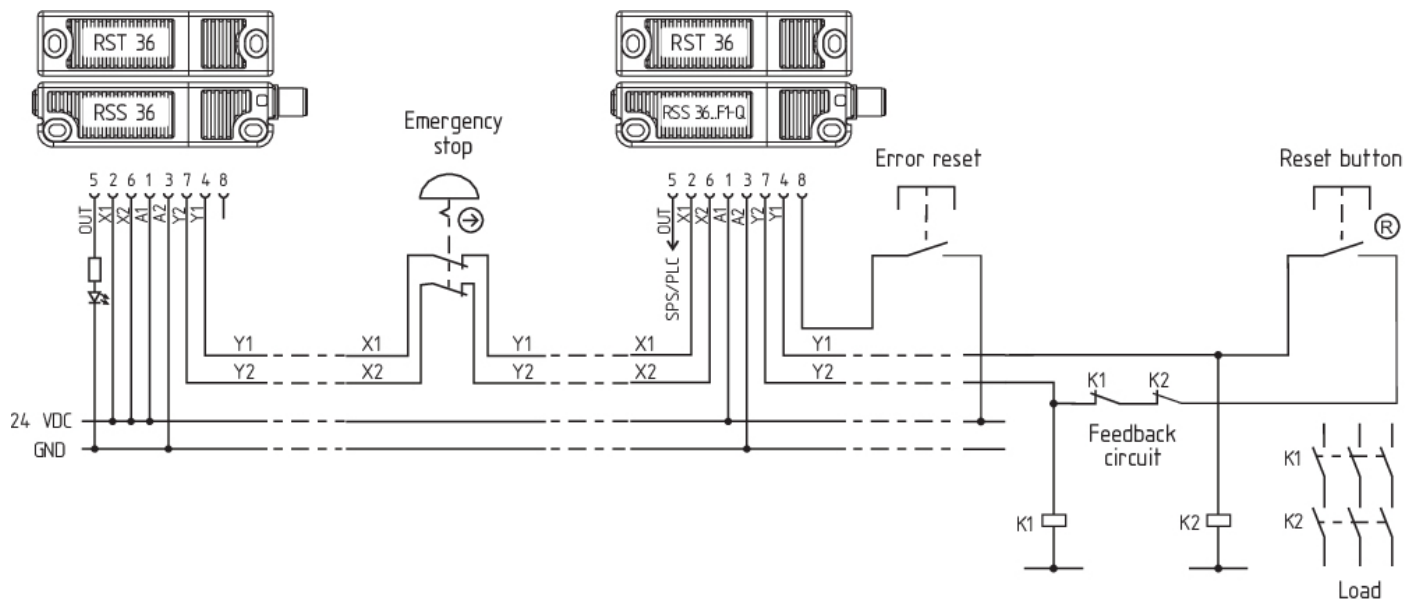
The feedback circuit can be extended by an enabling button. The sensor is switched on, as soon as the enabling button is pushed. The design then corresponds analogously to the wiring examples of the F1 variants. The internal safety-monitoring module of variant F0 is not equipped with an edge detection for the button. If required, a "manual reset" to EN ISO 13849-1 must be realised by other components of a local control system.



#### Wiring example 4: Series-wiring with RSS 36...F1-Q as master with EDM

The safety sensor RSS 36...F1 directly controls positive-action auxiliary contactors or relays. The F1 function also monitors a trailing edge of the reset button in addition to the feedback contacts. The sensor switches on when the button is released. It can be used for manual reset on safety guards, which can be stepped over. The protected area must be designed so that a single reset button suffices. The Q function monitors EMERGENCY STOP buttons integrated

into the chain and requires a separate error acknowledgement button.

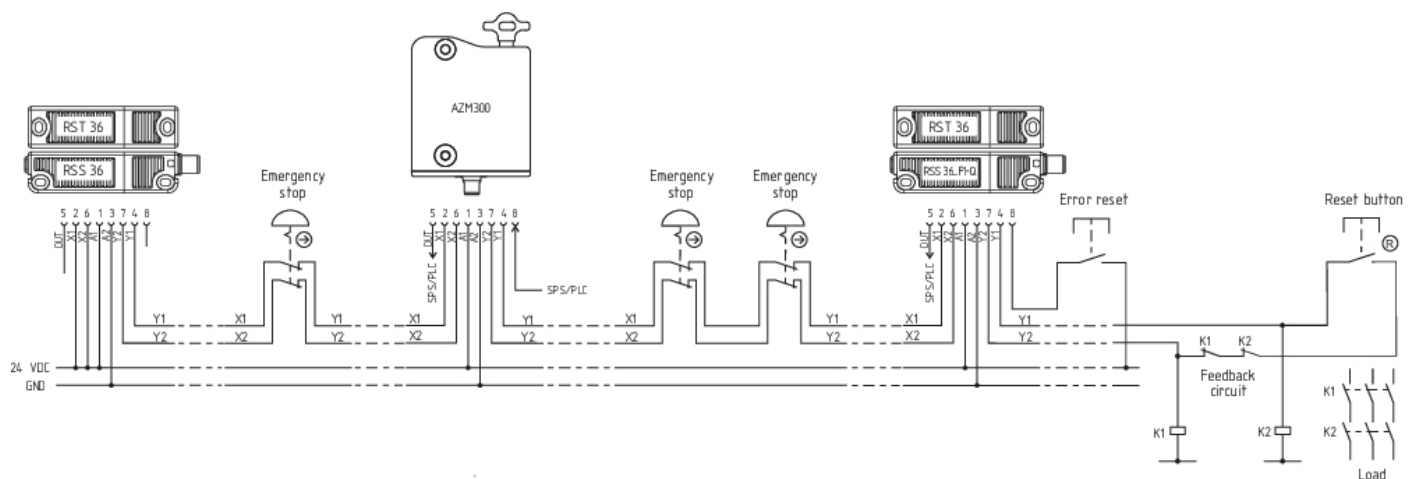


#### Wiring example 5: Series-wiring with RSS260...SD-F1-Q as master with EDM and serial diagnostics

The safety sensor RSS 260...F1 directly controls positive-action auxiliary contactors or relays. The F1 function also monitors a trailing edge of the reset button in addition to the feedback contacts. The sensor switches on when the button is released. It can be used for manual reset on safety guards, which can be stepped over. The protected area must be designed so that a single reset button suffices. The Q function monitors the EMERGENCY STOP buttons integrated into the chain. In the event of erroneous EMERGENCY STOP signals, the error message must be reset via the serial diagnostic channel using Q monitoring



#### Wiring example 5: Series-wiring with RSS 36...F1-Q with mixed components

The safety sensor RSS 36...F1 directly controls positive-action auxiliary contactors or relays. The F1 function also monitors a trailing edge of the reset button in addition to the feedback contacts. The sensor switches on when the button is released. It can be used for manual reset on safety guards, which can be stepped over. The protected area must be designed so that a single reset button suffices. The Q function monitors EMERGENCY STOP buttons integrated into the chain and requires a separate error acknowledgement button.



## 5.4 Wiring configuration and connector accessories



Function safety switchgear			Pin configuration of the connector		Colour codes of the Schmersal connectors			Poss. colour codes of other customary connectors
			8-pin version ST	5-pin version ST	8-pin version ST		5-pin version ST	to IEC 60947-5-2: 2007
	with conventional diagnostic output	with serial diagnostic function			IP67 / IP69 (PUR)	IP69 (PVC)	IP67 / IP69 (PUR)	
A1	Ue		1	1	WH	BN	BN	BN
X1	Safety input 1		2		BN	WH		WH
A2	GND		3	3	GN	BU	BU	BU
Y1	Safety output 1		4	4	YE	BK	BK	BK
OUT	Diagnoseausgang	SD-output	5	5	GY	GY	GY	GY
X2	Safety input 2		6		PK	VT		PK
Y2	Safety output 2		7	2	BU	RD	WH	VT
IN	without function	SD-input	8		RD	PK		OR

Connecting cables with coupling (female) IP67 / IP69, M12, 8-pole - 8 x 0.25 mm <sup>2</sup> to DIN 47100	
Cable length	Ordering code
2.5 m	103011415
5.0 m	103007358
10.0 m	103007359
15.0 m	103011414

Connecting cables (PVC) with socket (female) M12, 8-pole - 8 x 0.21 mm <sup>2</sup> IP69	
Cable length	Ordering code
5.0 m	101210560
5.0 m, angled	101210561
10.0 m	103001389
15.0 m	103014823

Connecting cables (PUR) with coupling (female) IP67 / IP69, M12, 5-pole - 5 x 0.34 mm <sup>2</sup> to EN 60947-5-2	
Cable length	Ordering code
5.0 m	103010816
10.0 m	103010818
15.0 m	103010820

Protection is not required when pilot wires are laid. The cables however must be separated from the supply and energy cables. The required electrical cable fuse protection must be integrated in the installation. The max. fuse rate for a sensor chain depends on the section of the connecting cable of the sensor.

## 6 Actuator coding

Safety sensors with standard coding are ready to use upon delivery.

Individually coded safety sensors and actuators will require the following "teach-in" procedure:

1. Energise the safety sensor.
2. Introduce the actuator in the detection range. The teach-in procedure is signalled at the safety sensor, red LED on, yellow LED flashes (1 Hz).
3. After 10 seconds, brief yellow cyclic flashes (3 Hz) request the switch-off of the operating voltage of the safety sensor. (If the voltage is not switched off within 5 minutes, the safety sensor cancels the "teach-in" procedure and signals a false actuator by 5 red flashes.)
4. Once the operating voltage is switched back on, the actuator must be detected once more in order to activate the actuator code that has been taught in. In this way, the activated code is definitively saved.

For ordering suffix -I1, the executed allocation of safety switchgear and actuator is irreversible.

For ordering suffix -I2, the "teach-in" procedure for a new actuator can be repeated an unlimited number of times.

When a new actuator is taught, the code, which was applicable until that moment, becomes invalid. Subsequent to that, an enabling inhibit will be active for ten minutes, thus providing for an increased protection against tampering. The green LED will flash until the expiration of the time of the enabling inhibit and the detection of the new actuator. In case of power failure during the lapse of time, the 10-minutes tampering protection time will restart.

## 7 Working principle and diagnostic function

### 7.1 Mode of operation of the safety outputs

The safety outputs can be integrated into the safety circuit of the control system.

The opening of a safety guard, i.e. the actuator is removed out of the active zone of the sensor, will immediately disable the safety outputs of the sensor.

### 7.2 Diagnostic-LEDs

The safety sensor indicates the operating condition and faults by means of three-colour LEDs located in the lateral surfaces of the sensor.












The following LED indicators are the same for safety sensors with conventional diagnostic output as for those with a serial diagnostic function.

The green LED indicates that the safety sensor is ready for operation. The supply voltage is on and all safety inputs are present.

Flashing (1Hz) of the green LED signals that a voltage is missing on one or both of the safety inputs (X1 and/or X2).

The yellow LED always signals the presence of an actuator within range. If the actuator is operating in the limit area of the sensor switching distance, it will be indicated by flashing.

The flashing can be used to prematurely detect variations in the clearance between the sensor and the actuator (e.g. sagging of a safety guard). The sensor must be adjusted before the distance to the actuator increases and before the safety outputs are disabled, thus stopping the machine. If an error is detected, the red LED will be activated.

LED indication (red)		Error cause
1 flash pulse		Error output Y1
2 flash pulses		Error output Y2
3 flash pulses		Cross-wire Y1/Y2
4 flash pulses		Ambient temperature too high
5 flash pulses		Incorrect or defective actuator
6 flash pulses		Discrepancy time error at X1/X2
Continuous red (yellow LED flashing)		Actuator teaching (if actuator within range)
Continuous red (possibly with yellow flashing LED)		Internal fault, with yellow flashing teaching procedure

## 7.3 Operating principle of the electronic diagnostic output

A diagnostic output additionally indicates the switching condition of the safety switchgear. These signals can be used in a downstream control.

The short-circuit proof diagnostic output OUT can be used for central visualisation or control tasks, e.g. in a PLC.

**The diagnostic output is not a safety-related output.**

### Error

Errors which no longer guarantee the function of the safety switchgear (internal errors) cause the safety outputs to be disabled within the duration of risk. After fault rectification, the error message is reset by opening and re-closing the corresponding safety guard.

### Error warning

A fault that does not immediately endanger the safety function of the safety switchgear (e.g. too high ambient temperature, safety output at external potential, cross-circuit) leads to delayed shutdown. This signal combination, diagnostic output disabled and safety channels still enabled, can be used to stop the production process in a controlled manner.

An error warning is deleted when the cause of error is eliminated.

If the fault warning remains on for 30 minutes, the safety outputs are also switched off (red LED flashes).

Table 1: Examples of the diagnostic function of the safety-sensor with conventional diagnostic output

Sensor function		LED's			Diagnostic-output	Safety outputs	Comments
		green	red	yellow			
I.	Supply voltage	On	Off	Off	0 V	0 V	Voltage on, no evaluation of the voltage quality
II.	Actuated	Off	Off	On	24 V	24 V	The yellow LED always signals the presence of an actuator within range.
III.	Actuated, actuator in limit area	Off	Off	Flashes (1Hz)	24 V pulsed	24 V	The sensor must be adjusted before the distance to the actuator increases and before the safety outputs are disabled, thus stopping the machine.
IV.	Internal error or in the event of simultaneous flashing, teach-in process	On	Off	Flashes (1Hz)	24 V	0 V	The sensor awaits a signal on the feedback circuit: F0: Closure of the feedback circuit F1: Falling edge on the feedback circuit
V.	Actuated in limit area and feedback circuit open	On	Off	flashes alternating (1Hz / 5Hz)	24 V pulsed	0 V	LED indication combines the sensor functions III. and IV.
VI.	Error warning, sensor actuated	Off	Flashes	Off	0 V	24 V	After 30 minutes if the error is not rectified
VII.	Error	Off	flashes / on	off / flashes	0 V	0 V	Refer to table with flash codes
VIII.	Teach actuator	Off	On	Flashes	0 V	0 V	Sensor in teaching mode
IX.	Protection time	Flashes	Off	Off	0 V	0 V	10 minutes pause after re-teaching
X.	No input signal at X1 and/or X2	Flashes (1Hz)	Off	Off	0 V	0 V	Example: door open; a door in the safety circuit upstream is also open.
XI.	No input signal at X1 and/or X2	Flashes (1Hz)	Off	On	24 V	0 V	Example: door closed, a door in the safety circuit upstream is open.

## 7.4 Safety-sensors with serial diagnostic function

Safety sensors with serial diagnostic cable have a serial input and output instead of the conventional diagnostic output. If RSS / CSS safety sensors are wired in series, the safety channels as well as the inputs and outputs of the diagnostic channels are wired in series.

Up to 31 safety switchgear devices can be connected in series with serial diagnostics. For the evaluation of the serial diagnostics line either the PROFIBUS-Gateway SD-I-DP-V0-2 or the Universal-Gateway SD-I-U-... are used. This SD-Gateway is integrated as a slave in an existing field bus system. In this way, the diagnostic signals can be evaluated by means of a PLC. The necessary software for the integration of the SD-Gateway is available for download at [products.schmersal.com](http://products.schmersal.com).

The response data and the diagnostic data are automatically and permanently written in the assigned input byte of the PLC for each safety sensor in the series-wired chain.

The request data for each safety sensor are transmitted to the device through an output byte of the PLC.

In the event of a communication error between the SD-Gateway and the safety sensor, the switching condition of the safety output of the safety sensor is maintained.

Bit 0: safety outputs enabled  
Bit 1: safety sensor actuated, actuator identified  
Bit 3: feedback circuit open or reset button not actuated  
Bit 4: both safety inputs live  
Bit 5: safety sensor actuated in hysteresis area  
Bit 6: error warning, switch-off delay activated  
Bit 7: error, safety outputs switched off

#### **Error**

Errors which no longer guarantee the function of the safety switchgear (internal errors) cause the safety outputs to be disabled within the duration of risk. The fault is reset, when the cause is eliminated and bit 7 of the request byte changes from 1 to 0 or the safety guard is opened. Faults at the safety outputs are only deleted upon the next release, as the fault rectification cannot be detected sooner.

#### **Error warning**

A fault that does not immediately endanger the safety function of the safety switchgear (e.g. too high ambient temperature, safety output at external potential, cross-circuit) leads to delayed shutdown. This signal combination, diagnostic output disabled and safety channels still enabled, can be used to stop the production process in a controlled manner.

An error warning is deleted when the cause of error is eliminated.

If the fault warning remains on for 30 minutes, the safety outputs are also switched off (red LED flashes).

#### **Diagnostic error (warning)**

If an error (warning) is signalled in the response byte, detailed fault information can be read out.



Detailed information about the use of the serial diagnostics can be found in the operating instructions of the PROFIBUS-Gateway SD-I-DP-V0-2 and the Universal-Gateway SD-I-U-....

Table 2: Function of the visual diagnostic LEDs, the serial status signals and the safety outputs by means of an example

System condition	LED's			Safety outputs	Status signals serial diagnostic byte Bit n°							
	green	red	yellow		7	6	5	4	3	2	1	0
Non-actuated, inputs X1 and X2 enabled	On	Off	Off	0 V	0	0	0	1	0	0	0	0
Actuated, feedback circuit open / not actuated	On	Off	Flashes (5Hz)	0 V	0	0	0	1	1	0	1	0
Actuated, safety outputs enabled	Off	Off	On	24 V	0	0	0	1	0	0	1	1
Actuated in limit area	Off	Off	Flashes (1Hz)	24 V	0	0	1	1	0	0	1	1
Actuated, warning	Off	On/flash es	Off	24 V	0	1	0	1	0	0	1	1
Actuated, fault	Off	On/flash es	Off	0 V	1	1	0	1	0	0	1	0

The shown bit order of the diagnostic byte is an example. A different combination of the operational conditions will lead to a change of the bit order.

Table 3: Tabular overview of status signals, warnings or error messages  
(The described condition is reached, when Bit = 1)

Communication directions:	Request byte:	from the PLC to the local safety sensor		
	Response byte:	from the local safety sensor to the PLC		
	Warning/error byte:	from the local safety sensor to the PLC		
Bit n°	Request byte	Response byte	Diagnostic	
□	□	□	Error warning	Error messages
Bit 0:	---	Safety output activated	Error output Y1	Error output Y1
Bit 1:	---	Actuator detected	Error output Y2	Error output Y2
Bit 2:	---	---	Cross-wire Y1/Y2	Cross-wire Y1/Y2
Bit 3:	---	---	Temperature too high	Temperature too high
Bit 4:	---	Input condition X1 and X2	---	Incorrect or defective actuator
Bit 5:	---	Actuated in limit area	Internal device error	Internal device error
Bit 6:	Error acknowledgement, Discrepancy time exceeded	Error warning	Communication error between the field bus Gateway and the safety switchgear	Error, discrepancy time exceeded at X1/X2
Bit 7:	Error reset	Error (enabling path switched off)	---	---

## 8 Set-up and maintenance

### 8.1 Functional testing

The safety function of the safety components must be tested. The following conditions must be previously checked and met:

1. Check fixation of the safety switch and the actuator
2. Fitting and integrity of the cable connections
3. The system is free of dirt and soiling (in particular metal chips).

Functional test after assembly and connection of the RSS 36---F0/-F1

All safety guards must be closed prior to the start of the functional test. The feedback circuit must be opened.<sup>1)</sup>

No.	Action to test the operation	Reaction RSS 36 F0 version	Reaction RSS 36 F1 version
1	Switch on the operating voltage	The yellow LED flashes at 5 Hz and the relays are disabled.	The yellow LED flashes at 5 Hz and the relays are disabled.
2	Close the feedback circuit: actuate the connected button <sup>2)</sup>	The yellow LED is on and both connected relays are enabled	No change compared to 1
3	Only version F1: reset button actuation	No change compared to 2	The yellow LED is on and both connected relays are enabled

<sup>1)</sup> If no button is used, the feedback circuit must be opened by loosening the cable. To that effect, the voltage must be switched off.

<sup>2)</sup> If no button is used, the feedback circuit must be closed by reconnecting the cable. To that effect, the voltage must be switched off.

With the F1 function, the button monitored on the falling edge must be actuated.

A non-monitored button integrated into the feedback circuit with function F0 is effective on closing.

An emergency-stop switching element integrated into series wiring can be monitored by the Q function in the last sensor of the chain. This monitors the simultaneous shutdown of its safety inputs and closes the safety outputs in the event of deviations greater than 500 ms. A malfunction in the chain detected in this way must be rectified immediately. Release is only then possible after the error has been acknowledged. The error will remain saved even in the event of a power interruption. Error acknowledgement must be effected via the negative edge of an acknowledge button connected to pin 8 or via the serial diagnosis line.

In addition, when emergency-stop switching elements are integrated, a reset button must be provided, as no automatic restart of the machine is permissible when an emergency-stop command is revoked.

As per the test interval referenced in the Maintenance chapter, the emergency-stop switching elements monitored in this way meet the requirements to PL e.

### 8.2 Maintenance

In the case of correct installation and adequate use, the safety switchgear features maintenance-free functionality. A regular visual inspection and functional test, including the following steps, is recommended:

1. Check the fixing and integrity of the safety switchgear, the actuator and the cable.
2. Remove possible metal chips.



Adequate measures must be taken to ensure protection against tampering either to prevent tampering of the safety guard, for instance by means of replacement actuators.



EMERGENCY STOP switching elements integrated into a series circuit with Q monitoring must have their function checked manually on a regular basis. An annual inspection is sufficient for a typical Cat. 3/PLd application. A monthly inspection is required for a typical Cat. 4/PLe application.



Damaged or defective components must be replaced.

## 9 Disassembly and disposal

### 9.1 Disassembly

The safety switchgear must be disassembled in a de-energised condition only.

### 9.2 Disposal



The safety switchgear must be disposed of in an appropriate manner in accordance with the national prescriptions and legislations.